Mixture Models

PUBH 8442: Bayes Decision Theory and Data Analysis

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PUBH 8442: Bayes Decision Theory and Data Analysis Mixture Models

Finite mixture models

▶ Let f_1, \ldots, f_K be densities with weights q_1, \ldots, q_k where

$$q_1 + q_2 + \cdots + q_K = 1$$
 and $q_k \ge 0 \forall k$.]

• Assume y_1, \ldots, y_n are iid with density

$$p(y_i) = \sum_{k=1}^{K} q_k f_k(y_i).$$



$$y_i \sim egin{cases} f_1 ext{ with probability } q_1 \ dots \ f_K ext{ with probability } q_k \ dots \ f_K ext{ with probability } q_k \end{cases}$$

- Useful for modeling complex distributions.
- *Mixture* of simpler *component* distributions f_k .

Dirichlet distribution

- ▶ In a Bayesian framework, put a prior on $q = (q_1, \ldots, q_K)$
- ► A *Dirichlet* prior is commonly used for *q*
 - Parameterized by concentration values $\alpha = (\alpha_1, \ldots, \alpha_K)$:

$$\pi(q) = rac{1}{B(lpha)} \prod_{k=1}^{K} q_k^{lpha_k - 1}$$

for $q_1 + q_2 + \cdots + q_K = 1$ and $q_k \ge 0 \ \forall \ k$.

B(·) is the multivariate beta function, defined by the gamma function Γ:

$$B(\alpha) = \frac{\prod_{k=1}^{K} \Gamma(\alpha_k)}{\Gamma(\sum_{k=1}^{K} \alpha_k)}$$

For
$$K = 2$$
, the Dirichlet $(\alpha_1, \alpha_2) = \mathsf{Beta}(\alpha_1, \alpha_2)$

Dirichlet distribution

• The domain of the Dirichlet is the K-1 unit simplex

$$\triangle^{K-1} = \left\{ q_1, \ldots, q_K \in \mathbb{R}^K : \sum_{k=1}^K q_k = 1 \text{ and } q_k \ge 0 \,\forall \, k \right\}$$

*α*₁ = ... = *α*_K = 1 implies a uniform distribution on *△^{K-1}* Dirichlet-multinomial model:

• Let z_1, \ldots, z_n be iid variables from K categories

•
$$z_i \in \{1, \ldots, K\}$$
 with $p(z_i = k) = q_k$

• Let n_k be the number of $z'_i s$ from category k.

$$(n_1,\ldots,n_k) \sim \mathsf{Multinomial}(n,q)$$

• The Dirichlet(α) is conjugate for *q*:

$$p(q | \mathbf{z}) = \text{Dirichlet}(\alpha_1 + n_1, \dots, \alpha_1 + n_K)$$

• We can also put a prior on (f_1, \ldots, f_K)

• Commonly assume f_k 's come from same parametric family:

$$f_k(\cdot) = f(\cdot \mid \theta_k)$$

and put a prior on $\theta_1, \ldots, \theta_k$

▶ For example, $f_k = \text{Normal}(\mu_k, \sigma_k^2)$ with independent priors

 $\mu_k \sim {\sf Normal}(\mu_0, au^2)$ $\sigma_k^2 \sim IG(a, b)$ on $heta_k = (\mu_k, \sigma_k^2)$ for $k = 1, \dots, K.$

Estimation

Let z_i ∈ {1,..., K} indicate the component that generated y_i
Gibbs sample from full conditionals for z, q, and (θ₁,..., θ_k):
Draw z_i, for i = 1,..., n, by

$$p(z_i = k \mid \mathbf{y}, q, \theta) \propto q_k f(y_i \mid \theta_k)$$

▶ Draw q by

 $p(q | \mathbf{y}, \theta, \mathbf{z}) = \mathsf{Dirichlet}(\alpha_1 + n_1, \dots, \alpha_K + n_K)$

where $n_k = \sum_{i=1}^n \mathbb{1}_{\{z_i = k\}}$ **b** Draw θ_k , for $k = 1, \dots, K$, from

 $p(heta_k \mid \mathbf{y}, q, z_i) \propto \pi(heta_k) f(\mathbf{y}_k \mid heta_k)$

where $\mathbf{y}_k = \{y_i : z_i = k\}$. This may require a Metropolis step, if conjugate prior s are not used.

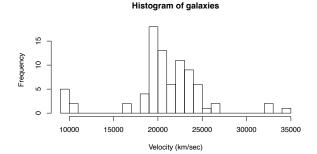
- Measurements taken from 82 galaxies in Corona Borealis region of space ¹
- Consider velocity in km/sec for each galaxy
 - Galaxies with a higher velocity are farther from earth.



¹Roeder, K. Density estimation with confidence sets exemplified by superclusters and voids in galaxies. *JASA* 85, 617-624.

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• The distribution of velocities (y) is very multimodal



http://www.ericfrazerlock.com/Mixture_Models_Rcode1.r

Model y as a mixture of normal densities:

$$p(y_i \mid q, (\mu_k, \sigma_k^2)_{k=1}^K) \stackrel{iid}{=} \sum_{k=1}^K q_k \operatorname{Normal}(y_i \mid \mu_k, \sigma_k^2)$$

for i = 1, ..., n.

Use a uniform Dirichlet prior for q

 $q \sim \mathsf{Dirichlet}(\mathbf{1})$

• Use a mildy informative normal-inverse-gamma prior for μ_k, σ_k^2 : $\mu_k \stackrel{iid}{\sim} \text{Normal}(20000, 10^9)$

$$\sigma_k^2 \stackrel{iid}{\sim} IG(2, 10^8)$$

- Estimate for K = 4 clusters
- ▶ For Gibbs sampling, initialize:
 - Draw μ_k, σ_k^2 from prior for $k = 1, \dots, 4$
 - Set $q_k = 1/4$ for k = 1, ..., 4

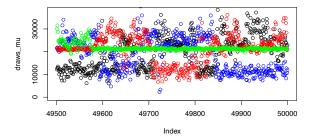
- ► The full conditional for each $\mu_k \sigma_k^2$ can be drawn from a normal-inverse-gamma posterior.
- ▶ Run Gibbs sampling for T = 50000 iterations

R CODE

```
for(t in 1:T){ ##Run gibbs sampler
 ###Generate component indicators Z
 for(k in 1:K) probs[k,] = q[k]*dnorm(y,mu[k],sqrt(sigma2[k]))
 for(i in 1:n) Z[i] = which(rmultinom(1,1,probs[,i])==1)
 ###Generate qs
 nk = c()
 for(k in 1:K) nk[k] = sum(Z==k)
 q = rdirichlet(1,alpha+nk)
 ###generate mu_k, sigma2_k from normal-inverse-gamma posterior
 for(k in 1:K){
   a_{post} = a + nk[k]/2 - 1/2
   b_post = b+(1/2)*sum((y[Z==k]-mean(y[Z==k]))^2)
   sigma2[k] = 1/rgamma(1,a_post,b_post)
   post_mu_mean = (sigma2[k]*mu0+tau2*sum(y[Z==k]))/(nk[k]*tau2+
   post_mu_var = sigma2[k]*tau2/(nk[k]*tau2+sigma2[k])
   mu[k] = rnorm(1,post_mu_mean,sqrt(post_mu_var))
 }
```

```
##Store draws
draws_q[t,] = q
draws_mu[t,] = mu
draws_sigma2[t,] = sigma2
###Compute density over grid
x = seq(from = 5000, to=40000, length.out=200)
Dens = rep(0,200)
for(k in 1:K) Dens = Dens+q[k]*dnorm(x,mu[k],sqrt(sigma2[]
draws_dens[t,] = Dens
}
```

• Plot of posterior draws for $\mu_1, \mu_2, \mu_3, \mu_4$, last 500 iterations:

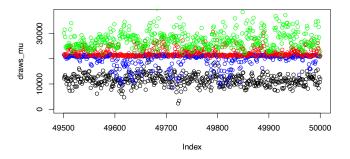


http://www.ericfrazerlock.com/Mixture_Models_Rcode1.r

• Chains cross - "label switching"

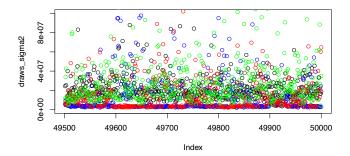
```
for(t in 1:T){
    Order = order(draws_mu[t,])
    draws_q[t,] = draws_q[t,Order]
    draws_mu[t,] = draws_mu[t,Order]
    draws_sigma2[t,] = draws_sigma2[t,Order]
}
```

• Maintaining order $\mu_1 < \mu_2 < \mu_4 < \mu_4$:

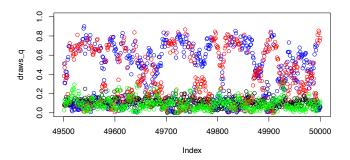


• Keep these labels for subsequent computation

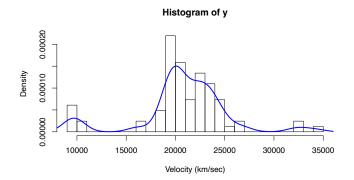
• Final 500 draws for $\sigma_1^2, \sigma_2^2, \sigma_3^2, \sigma_4^2$:



• Final 500 draws for *q*₁, *q*₂, *q*₃, *q*₄:



• Density estimate based on posterior draws:



Component estimates:

•
$$\mu_1 = 11529, \ \sigma_1^2 = 28397532, \ q_1 = 0.10$$

•
$$\mu_2 = 19501, \ \sigma_2^2 = 24032751, \ q_2 = 0.40$$

$$\blacktriangleright \ \mu_3 = 22566, \ \sigma_3^2 = 18692368, \ q_3 = 0.40$$

•
$$\mu_4 = 27818, \ \sigma_4^2 = 34797849, \ q_4 = 0.10$$

- Number of components (i.e., *clusters*) K can be selected using standard model selection tools
- ▶ DIC, BIC, cross-validation, etc.
- ► Alternatively, put a prior on K
- Or, choose K large and use small values for α
 - Some components will have negligable probability
- Letting $K \to \infty$ with $\alpha_k = c/K$ for all k gives a Dirichlet process.